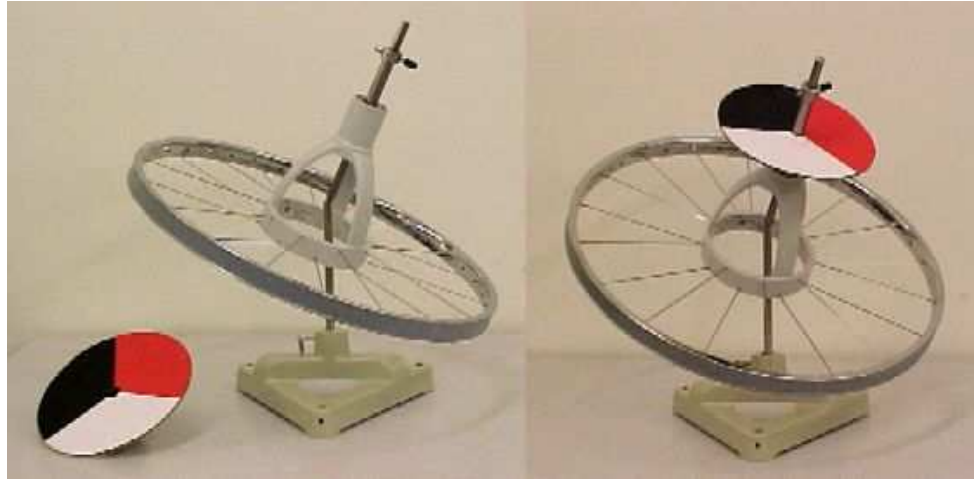


# Nutation (1)

Aim: To show nutation.

Subjects: 1Q50 (Gyros)

Diagram:



Equipment:

- Large gyroscope (Leybold 34818)
- Pointed rod
- Rod with cup
- Round disk with red, white and black segments

# Nutation (1)

Presentation: The pointed support is shifted so that the gyroscope is supported at its centre of gravity. The gyroscope is made spinning at an angle of about  $20^\circ$  with the vertical. The spinning gyroscope remains steady in space.

Now a short blow is given to the axis of the spinning gyroscope. It now performs an additional rotary motion; the axis moves conically. This movement is called nutation.

If the colored segment is fixed on the top-side of the ballbearing, the instantaneous axis of spin is made visible. (Individual colors will be seen, but everywhere else they will merge to a uniform 'grey'.)

Explanation: When the gyroscope is spinning, it has an angular momentum of  $I_0\omega_0$  (see Figure1). When a short blow is given, an extra angular momentum ( $\Delta L$ ) is added to the spinning wheel (see Figure2; the short blow is given to the upper part of the axis in the direction of the observer). This leads to a total angular momentum  $L$ , which is constant from then on.

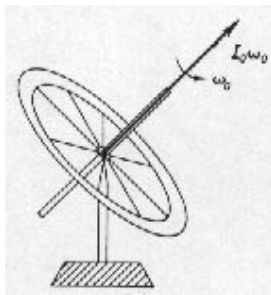


Figure 1

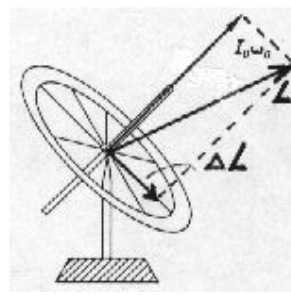


Figure 2

$\Delta L$  corresponds with a rotation  $\omega' = \frac{\Delta L}{I'}$ . The resultant of  $\omega_0$  and  $\omega'$  is the momentary

angular velocity  $\omega$  (see Figure3). This resultant  $\omega$  does not have the same direction as  $L$ , since  $I' < I_0$ . The constant  $L$  is, at any moment, the resultant of  $I_0\omega_0$  and  $I'\omega'$ . This is reached only when the gyroscope moves in such a way that in the parallelogram of Figure 4, the axis of momentary angular velocity moves in a cone around the fixed axis of  $L$ . Then also the symmetry-axis of the gyroscope moves in a cone around the axis of  $L$ . This cone is called the cone of nutation.

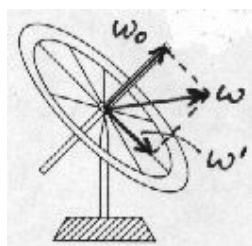


Figure 3

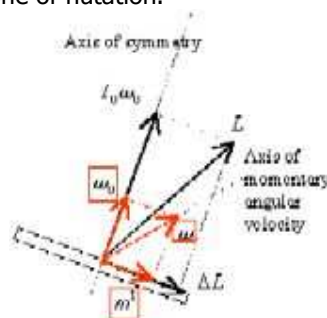


Figure 4

For the observer in the laboratory, this results in a rotation of the coplanar vectors  $\omega_0$ ,  $I_0\omega_0$ ,  $\omega$ ,  $\Delta L$  and  $\omega'$  around  $L$ . The cone described by the symmetry-axis around  $L$  is called the cone of nutation; the cone described by  $\omega$  around  $L$  is called the space cone. For the observer in the rotating frame (e.g. seated on the symmetry-axis), the vector  $\omega$  rotates around this axis, thus describing the so-called body cone. For the observer in the

# Nutation (1)

laboratory, this cone is not stationary, but moves around the space cone. Notice that the space cone and the body cone have the vector  $\omega$  in common.

Remarks:

- See also the description of the demonstration "Nutation (2)" in this database.

Sources:

- [Roest, R., Inleiding Mechanica](#), pag. 223
- [Borghouts, A.N., Inleiding in de Mechanica](#), pag. 225
- [Leybold Didactic GmbH, Gerätekarte](#), 34818